

1, a,

$$\boxed{3} \det \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{m1} & \dots & a_{mn} \end{bmatrix} = \sum_{\sigma \in S_n} I(\sigma) \cdot a_{1, \sigma(1)} \cdot a_{2, \sigma(2)} \cdot \dots \cdot a_{n, \sigma(n)},$$

ahol S_n az n -edrendű permutációk csoportja, tehát $\sigma \in S_n$ az $\{1, \dots, n\}$ halmazon egy permutációja, és $I(\sigma) = \begin{cases} +1, & \text{ha } \sigma \text{ páros permutáció} \\ -1, & \text{ha } \sigma \text{ páratlan permutáció} \end{cases}$.

$\boxed{2}$ b, T: Ha két sor egyenlő, azaz Pl.: $a_{i,k} = a_{j,k} \quad \forall k \in \{1, \dots, n\}$, ahol $i, j \in \{1, \dots, n\}, i \neq j$, akkor a determináns zérus.

C, B: Ha $a_{i,k} = a_{j,k} \quad \forall k \in \{1, \dots, n\}$, akkor *

$$\boxed{5} \quad a_{1, \sigma(1)} \cdot \dots \cdot a_{i, \sigma(i)} \cdot \dots \cdot a_{j, \sigma(j)} \cdot \dots \cdot a_{n, \sigma(n)} = \prod_l a_{l, \sigma'(l)} =$$

$$= a_{1, \sigma(1)} \cdot \dots \cdot a_{i, \sigma(j)} \cdot \dots \cdot a_{j, \sigma(i)} \cdot \dots \cdot a_{n, \sigma(n)} = \prod_l a_{l, \sigma'(l)}$$

\uparrow
 $a_{i, \sigma'(j)}$

\uparrow
 $a_{j, \sigma'(i)}$

* legyen

$$\sigma'(l) = \begin{cases} \sigma(l), & \text{ha } l \neq i, l \neq j \\ \sigma(j), & \text{ha } l = i \\ \sigma(i), & \text{ha } l = j \end{cases}$$

Továbbá $I(\sigma) = -I(\sigma')$, Ez azt jelenti, hogy a determinánsban szereplő tényező pontosan kétféleképpen egyenlő.

2, Leppen $\underline{i} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$; $\underline{j} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$; $\underline{k} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$; Eller $\underline{v} = \underline{i} + 2\underline{j}$

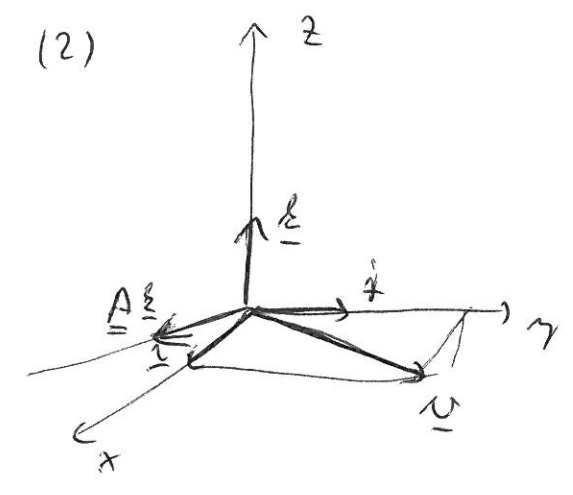
$A\underline{v} = 2\underline{v} \implies A\underline{i} + 2A\underline{j} = 2\underline{i} + 4\underline{j}$ (1)

Mivel $\underline{k} \perp \underline{v}$, ezért $A\underline{k}$ az $(\underline{i}, \underline{j})$ síkban esik, és $A\underline{k} \perp \underline{v}$,

tehát $A\underline{k} = \frac{1}{\sqrt{5}} \begin{bmatrix} 2 \\ -1 \\ 0 \end{bmatrix} = \frac{2}{\sqrt{5}} \underline{i} - \frac{1}{\sqrt{5}} \underline{j}$ (2)

$A^2 \underline{k} = -\underline{k}$, tehát

$\frac{2}{\sqrt{5}} A\underline{i} - \frac{1}{\sqrt{5}} A\underline{j} = -\underline{k}$ (3)



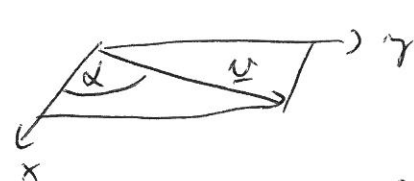
(3) $\cdot 2\sqrt{5} + (1)$: $5A\underline{i} = 2\underline{i} + 4\underline{j} - 2\sqrt{5}\underline{k}$

(3) $- (1) \cdot \frac{2}{\sqrt{5}}$: $-\sqrt{5}A\underline{j} = -\frac{4}{\sqrt{5}}\underline{i} - \frac{8}{\sqrt{5}}\underline{j} - \underline{k}$

Tehát $[A] = \left[\begin{array}{c|c|c} A\underline{i} & A\underline{j} & A\underline{k} \end{array} \right] = \begin{bmatrix} 2/5 & 4/5 & 2/\sqrt{5} \\ 4/5 & 8/5 & -1/\sqrt{5} \\ -2/\sqrt{5} & 1/\sqrt{5} & 0 \end{bmatrix}$

Más lepp. Leppen O_z^α a z körülbelül α szögű forgatás, O_x^β pedig az x tengely körül β szögű, és $N_x^{(2)}$ az x irányú 2-szeres nyújtás

$A = O_z^\alpha N_x^{(2)} O_x^\beta O_z^{-\alpha}$, ahol α az x tengely és \underline{v} szög, tehát



$\cos \alpha = \frac{1}{\sqrt{5}}$; $\sin \alpha = \frac{2}{\sqrt{5}}$

$A = \begin{bmatrix} \frac{1}{\sqrt{5}} & -\frac{2}{\sqrt{5}} & 0 \\ \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{5}} & \frac{2}{\sqrt{5}} & 0 \\ -\frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 2/5 & 4/5 & 2/\sqrt{5} \\ 4/5 & 8/5 & -1/\sqrt{5} \\ -2/\sqrt{5} & 1/\sqrt{5} & 0 \end{bmatrix}$

$\begin{bmatrix} 2/\sqrt{5} & 0 & 2/\sqrt{5} \\ 4/\sqrt{5} & 0 & -1/\sqrt{5} \\ 0 & 1 & 0 \end{bmatrix}$

[-3-1]

$$\begin{array}{l} 3 \\ \text{10} \end{array} \left[\begin{array}{cccc|c} 2 & -1 & -2 & 1 & 0 \\ -1 & +1 & 2 & 2 & -7 \\ 3 & +2 & +4 & 0 & 8 \\ 1 & 0 & 0 & 1 & -1 \end{array} \right] \begin{array}{l} \leftarrow \\ \leftarrow \\ \leftarrow \\ \leftarrow \end{array} \begin{array}{l} (-2) \\ (-3) \\ +1 \end{array} \Rightarrow \left[\begin{array}{cccc|c} 0 & -1 & -2 & -1 & 2 \\ 0 & 1 & 2 & 3 & -8 \\ 0 & 2 & 4 & -3 & 11 \\ 1 & 0 & 0 & 1 & -1 \end{array} \right] \begin{array}{l} \leftarrow +1 \\ \leftarrow (-2) \times \Rightarrow \end{array}$$

$$\Rightarrow \left[\begin{array}{cccc|c} 0 & 0 & 0 & 2 & -6 \\ 0 & 1 & 2 & 3 & -8 \\ 0 & 0 & 0 & -9 & 27 \\ 1 & 0 & 0 & 1 & -1 \end{array} \right] \begin{array}{l} /: 2 \\ /: -9 \end{array} \Rightarrow \left[\begin{array}{cccc|c} 0 & 0 & 0 & 1 & -3 \\ 0 & 1 & 2 & 3 & -8 \\ 0 & 0 & 0 & 1 & -3 \\ 1 & 0 & 0 & 1 & -1 \end{array} \right] \begin{array}{l} \leftarrow \\ \leftarrow \\ \leftarrow \end{array} \Rightarrow \left[\begin{array}{cccc|c} 0 & 0 & 0 & \textcircled{1} & -3 \\ 0 & \textcircled{1} & 2 & 0 & +1 \\ \hline 0 & 0 & 0 & 0 & 0 \\ \textcircled{1} & 0 & 0 & 0 & +2 \end{array} \right]$$

Tehtävä $x=2$, $y+2z=1$; $w=-3$; $t=3$ (vääntömomentit nimen)

4, a, $|A - \lambda I| = \begin{vmatrix} 1-\lambda & 2 \\ 1 & 1-\lambda \end{vmatrix} = (1-\lambda)^2 - 2 = \lambda^2 - 2\lambda - 1$

$$\lambda_{1,2} = 1 \pm \sqrt{1+1} = \underline{1 \pm \sqrt{2}} \quad \textcircled{2}$$

$$\lambda_1 = 1 + \sqrt{2}; \quad \underbrace{\begin{bmatrix} -\sqrt{2} & 2 \\ 1 & -\sqrt{2} \end{bmatrix}}_{A - \lambda_1 I} \begin{bmatrix} x \\ y \end{bmatrix} = \underline{0} \Rightarrow \begin{array}{l} -\sqrt{2}x + 2y = 0 \\ x - \sqrt{2}y = 0 \end{array} \Rightarrow \underline{u_1 = \begin{bmatrix} \sqrt{2} \\ 1 \end{bmatrix}} \quad \textcircled{2}$$

$$\lambda_2 = 1 - \sqrt{2}; \quad \begin{bmatrix} \sqrt{2} & 2 \\ 1 & \sqrt{2} \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \underline{0} \Rightarrow \begin{array}{l} \sqrt{2}x + 2y = 0 \\ x + \sqrt{2}y = 0 \end{array} \Rightarrow \underline{u_2 = \begin{bmatrix} -\sqrt{2} \\ 1 \end{bmatrix}} \quad \textcircled{2}$$

4, b, $B(p) \cdot B^*(p) - B^*(p) \cdot B(p) = \begin{bmatrix} 1 & p \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ p & 1 \end{bmatrix} - \begin{bmatrix} 1 & 1 \\ p & 1 \end{bmatrix} \begin{bmatrix} 1 & p \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 1+p^2 & 1+p \\ 1+p & 2 \end{bmatrix} - \begin{bmatrix} 2 & 1+p \\ 1+p & 1+p^2 \end{bmatrix} = \begin{bmatrix} p^2-1 & 0 \\ 0 & 1-p^2 \end{bmatrix} \Rightarrow B \text{ normaali, kun } p^2-1=0, \text{ } \underline{\text{koska kun } p = \pm 1} \quad \textcircled{2}$

$B(p)$ ortogonaalinen, kun $p=1$ $\textcircled{1}$

$B(p)$ invertiteltävyys, kun $\det B(p) = 1-p \neq 0$, koska $p \neq 1$ $\textcircled{1}$

5, a,

$$\textcircled{6} \operatorname{div}(\underline{r} \times \underline{v}(\underline{r})) = \partial_i (\varepsilon_{jki} r_j v_k) = \varepsilon_{jki} (\overbrace{\partial_i r_j}^{j_{ij}}) v_k + r_j (\partial_i v_k) =$$

$$= \underbrace{\varepsilon_{jki} v_k}_0 + r_j \varepsilon_{jki} (\partial_i v_k) = \underline{-r \cdot \operatorname{rot} v}$$

6, b,

$$\textcircled{4} \underline{r} \times \underline{v}(\underline{r}) = \begin{bmatrix} x \\ y \\ z \end{bmatrix} \times \begin{bmatrix} x^2 y \\ 2x - yz \\ 3z \end{bmatrix} = \begin{bmatrix} 3yz - 2xz + yz^2 \\ x^2 yz - 3xz \\ 2x^2 - xy z - x^2 y^2 \end{bmatrix};$$

$$\operatorname{div}(\underline{r} \times \underline{v}(\underline{r})) = \underline{-2z + zx^2 - xy}$$

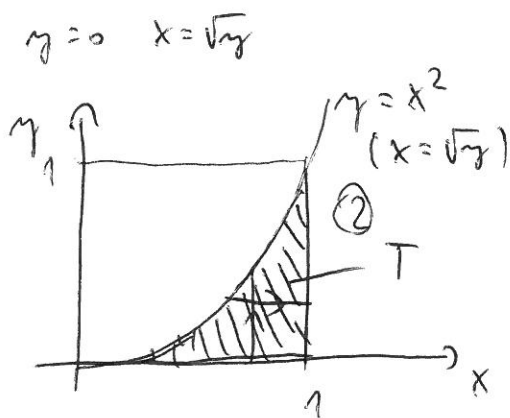
Weg messen:

$$\textcircled{4} \operatorname{rot} \underline{v} = \begin{bmatrix} 0 - (-y) \\ 0 - 0 \\ 2 - x^2 \end{bmatrix} = \begin{bmatrix} y \\ 0 \\ 2 - x^2 \end{bmatrix};$$

$$-r \cdot \operatorname{rot} v = \underline{-xy - 2z + zx^2} \quad \checkmark$$

6,

$$\textcircled{10} \int_0^1 \int_0^1 \sin(x^3) dx dy = \int_{x=0}^1 \int_{y=0}^{x^2} \sin(x^3) dy dx = \textcircled{4}$$



$$= \int_{x=0}^1 \sin(x^3) \cdot x^2 dx = \frac{1}{3} \int_{x=0}^1 \sin(x^3) (3x^2) dx =$$

$\int \sin \varphi \cdot \varphi' dx$

$$= \left[\frac{-\cos(x^3)}{3} \right]_0^1 = \underline{\underline{\frac{-\cos(1)}{3} + \frac{1}{3}}} \quad \textcircled{4}$$