

1, \underline{D}_1 : A \mathbb{W} vektortérben az $\{\underline{v}_i\}_{i \in I}$ $C\mathbb{W}$ rendszer lineárisan független,
 ha $\sum_{k=1}^m \alpha_k \underline{v}_{i_k} = \underline{0}$ esetén $\alpha_k = 0 \forall k \in \{1, 2, \dots, m\}$ ($i_k \in I$)

\underline{D}_2 : $\{\underline{v}_i\}_{i \in I}$ generátorrendszer, ha $\forall \underline{x} \in \mathbb{W}$ esetén $\exists i_k \in I$,
 $\alpha_k \in \mathbb{R}$ ($k=1, 2, \dots, m$), hogy $\sum_{k=1}^m \alpha_k \underline{v}_{i_k} = \underline{x}$

\underline{D}_3 : $\{\underline{v}_i\}_{i \in I}$ $C\mathbb{W}$ lineáris \mathbb{W} -ben, ha lin. független és gene-
 rátorrendszer.

\underline{b}_1 legyen $\{\underline{b}_i\}_{i \in I}$ $C\mathbb{W}$ lineáris, mivel generátorrendszer, ezért minden
 vektor kifejezhető. T.Á.L. $\underline{v} \in \mathbb{W}$ kifejezhető i kifejezhető,

azaz $\underline{v} = \sum_{k=1}^m \alpha_k \underline{b}_{i_k} = \sum_{l=1}^m \beta_l \underline{b}_{j_l}$. Ekkor

$$\underline{0} = \sum_{k=1}^m \alpha_k \underline{b}_{i_k} - \sum_{l=1}^m \beta_l \underline{b}_{j_l}, \quad \alpha_k, \beta_l \neq 0, \text{ ami ellent-}$$

mondásnak, hogy $\{\underline{b}_i\}_{i \in I}$ lin. független rendszer.

2, $\alpha, \beta, p_1, p_2 \in \mathbb{P}$; $\alpha, \beta \in \mathbb{R}$ esetén

$$(A(\alpha p_1 + \beta p_2))(x) = (\alpha p_1 + \beta p_2)(x-1) = \alpha p_1(x-1) + \beta p_2(x-1) =$$

$$= \alpha (A p_1)(x) + \beta (A p_2)(x) \quad \forall x \in \mathbb{R} \text{ esetén, tehát}$$

$$A(\alpha p_1 + \beta p_2) = \alpha A p_1 + \beta A p_2 \quad \checkmark$$

\underline{b}_1 legyen $b_k(x) = x^k, \quad k=0, 1, 2, 3.$

$$(A b_0)(x) = b_0(x-1) = 1$$

$$(A b_1)(x) = b_1(x-1) = x-1 = (b_1 - b_0)(x)$$

$$(A b_2)(x) = b_2(x-1) = (x-1)^2 = x^2 - 2x + 1 =$$

$$= (b_2 - 2b_1 + b_0)(x)$$

$$(A b_3)(x) = b_3(x-1) = (x-1)^3 = x^3 - 3x^2 + 3x - 1 =$$

$$= (b_3 - 3b_2 + 3b_1 - b_0)(x)$$

$$[A] = \begin{bmatrix} 1 & -1 & 1 & -1 \\ 0 & 1 & -2 & 3 \\ 0 & 0 & 1 & -3 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$3, \quad A = \begin{bmatrix} 2 & -2 \\ -2 & -1 \end{bmatrix}; \quad |A - \lambda I| = \begin{vmatrix} 2-\lambda & -2 \\ -2 & -1-\lambda \end{vmatrix} = \lambda^2 - \lambda - 2 - 4 = \lambda^2 - \lambda - 6 = \\ = (\lambda - 3)(\lambda + 2) \Rightarrow \underline{\lambda_1 = -2; \lambda_2 = 3}$$

$$\lambda_1 = -2: \quad \underbrace{\begin{bmatrix} 4 & -2 \\ -2 & 1 \end{bmatrix}}_{A - \lambda_1 I} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow \begin{cases} 4x - 2y = 0 \\ -2x + y = 0 \end{cases} \Rightarrow \underline{v_{-1} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \cdot \frac{1}{\sqrt{5}}}$$

$$\underline{P_1 = v_{-1} \cdot v_{-1}^T = \frac{1}{5} \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix}}$$

$$\lambda_2 = +3 \quad \underline{P_2 = I - P_1 = \frac{1}{5} \begin{bmatrix} 4 & -2 \\ -2 & 1 \end{bmatrix}}$$

$$\underbrace{\begin{bmatrix} -1 & -2 \\ -2 & -4 \end{bmatrix}}_{A - \lambda_2 I} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow \begin{cases} -x - 2y = 0 \\ -2x - 4y = 0 \end{cases} \Rightarrow \underline{v_{-2} = \begin{bmatrix} 2 \\ -1 \end{bmatrix} \cdot \frac{1}{\sqrt{5}}}$$

$$A \text{ spektral förenten: } \underline{A = \lambda_1 P_1 + \lambda_2 P_2 = -2 \cdot \frac{1}{5} \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} + 3 \cdot \frac{1}{5} \begin{bmatrix} 4 & -2 \\ -2 & 1 \end{bmatrix}}$$

$$\underline{e^A = e^{\lambda_1 P_1} + e^{\lambda_2 P_2} = e^{-2} \cdot \frac{1}{5} \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} + e^3 \cdot \frac{1}{5} \begin{bmatrix} 4 & -2 \\ -2 & 1 \end{bmatrix}}$$

$$4, \quad \underline{r(t)} = \begin{bmatrix} t \\ t^2 \\ t^3 \end{bmatrix}; \quad \underline{\dot{r}(t)} = \begin{bmatrix} 1 \\ 2t \\ 3t^2 \end{bmatrix}; \quad \underline{\ddot{r}(t)} = \begin{bmatrix} 0 \\ 2 \\ 6t \end{bmatrix}$$

$$\underline{r(t_0)} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}; \quad \underline{\dot{r}(t_0)} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}; \quad \underline{\ddot{r}(t_0)} = \begin{bmatrix} 0 \\ 2 \\ 6 \end{bmatrix}; \quad \underline{\dot{r}(t_0)} \times \underline{\ddot{r}(t_0)} = \begin{bmatrix} 6 \\ -6 \\ 2 \end{bmatrix}$$

$$G(t_0) = \frac{|\dot{r}(t_0) \times \ddot{r}(t_0)|}{|\dot{r}(t_0)|^3} = \frac{\sqrt{36+36+4}}{(\sqrt{1+4+9})^3} = \frac{\sqrt{76}}{\sqrt{14^3}}$$

A minuter och normalvektorn avsees $\underline{\dot{r}} \times \underline{\ddot{r}} - t_0 \underline{e}$; $\underline{e} = \begin{bmatrix} 3 \\ -3 \\ 1 \end{bmatrix}$

A mitte eppendite:

$$\boxed{3x - 3y + z = 1}$$

$$\underline{r(t_0)} \cdot \underline{e} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 3 \\ -3 \\ 1 \end{bmatrix} = 3 - 3 + 1 = 1$$

$$5^* \quad a_i [\text{rot}(f \underline{v})]_i = \varepsilon_{ijk} \partial_j (f v_k) = \varepsilon_{ijk} ((\partial_j f) v_k + f \partial_j v_k) =$$

$$= [\text{grad } f \times \underline{v} + f \text{rot } \underline{v}]_i$$

$$b, \quad f(x, y, z) = x^2 y + z; \quad \text{grad } f = \begin{bmatrix} 2xy \\ x^2 \\ 1 \end{bmatrix}; \quad \underline{v} = \begin{bmatrix} xy \\ z^2 + 2x \\ xyz \end{bmatrix}$$

$$\text{grad } f \times \underline{v} = \begin{bmatrix} x^3 y z - (z^2 + 2x) \\ xy - 2x^2 y^2 z \\ 2xy(z^2 + 2x) - x^3 y \end{bmatrix}$$

$$\text{rot } \underline{v} = \begin{bmatrix} xz - 2z \\ 0 - yz \\ 2 - x \end{bmatrix}; \quad f \text{rot } \underline{v} = \begin{bmatrix} (xz - 2z)(x^2 y + z) \\ -yz(x^2 y + z) \\ (2 - x)(x^2 y + z) \end{bmatrix}$$

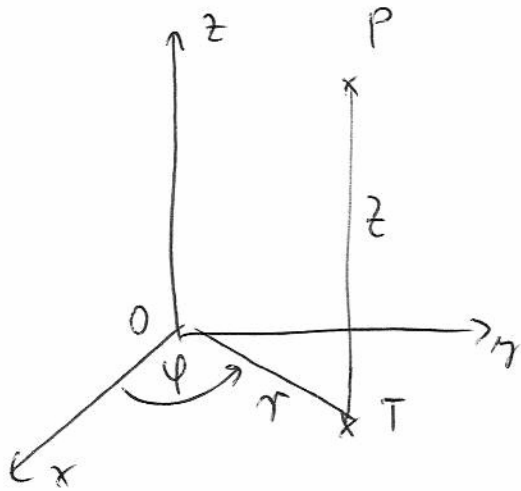
$$\text{Zusatz addiert: } \begin{bmatrix} x^3 y z - (z^2 + 2x) + (xz - 2z)(x^2 y + z) \\ xy - 2x^2 y^2 z - yz(x^2 y + z) \\ 2xy(z^2 + 2x) - x^3 y + (2 - x)(x^2 y + z) \end{bmatrix}$$

$$f \underline{v} = \begin{bmatrix} x^3 y^2 + x y z \\ x^2 y z^2 + z^3 + 2x^3 y + 2xz \\ x^3 y^2 z + x y z^2 \end{bmatrix};$$

$$\text{Zusatz addiert: } \text{rot}(f \underline{v}) = \begin{bmatrix} 2x^3 y z + xz^2 - (2x^2 y z + 3z^2 + 2x) \\ xy - 3x^2 y^2 z - yz^2 \\ 2xy z^2 + 6x^2 y + 2z - 2x^3 y - xz \end{bmatrix}$$

-4-

6 #
a,



$$r = \overline{OT}; \quad z = \overline{TP}$$

$$\left. \begin{aligned} x &= r \cos \varphi \\ y &= r \sin \varphi \\ z &= z \end{aligned} \right\}$$

$$J(r, \varphi, z) = \begin{vmatrix} x'_r & x'_\varphi & x'_z \\ y'_r & y'_\varphi & y'_z \\ z'_r & z'_\varphi & z'_z \end{vmatrix} =$$

$$= \begin{vmatrix} \cos \varphi & -r \sin \varphi & 0 \\ \sin \varphi & r \cos \varphi & 0 \\ 0 & 0 & 1 \end{vmatrix} = r (\cos^2 \varphi + \sin^2 \varphi) = \underline{\underline{r}}$$

b,

$$x^2 + y^2 \leq 6$$

$$0 \leq z \leq 6 - x^2 - y^2$$

(\Rightarrow)

$$\left. \begin{aligned} 0 &\leq r \leq 2 \\ 0 &\leq \varphi \leq 2\pi \\ 0 &\leq z \leq 6 - r^2 \end{aligned} \right\}$$

$$V = \int_{\varphi=0}^{2\pi} \int_{r=0}^2 \int_{z=0}^{6-r^2} 1 \cdot \underset{\text{Jac. det.}}{r} dz dr d\varphi =$$

$$= 2\pi \int_{r=0}^2 r (6 - r^2 - 0) dr =$$

$$= 2\pi \int_{r=0}^2 (6r - r^3) dr = 2\pi \left[-\frac{r^4}{4} + 6 \frac{r^2}{2} \right]_0^2 =$$

$$= 2\pi (-4 + 3 \cdot 4) = \underline{\underline{16\pi}}$$

