Simulations in Statistical Physics Course for MSc physics students

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Spreading on networks

- Diffusion
- ► Random walk
- ▶ Disease USA UK

► Master egyenlet:

$$\frac{\partial n(i)}{\partial t} = \frac{1}{2} [n(i-1) - 2n(i) + n(i+1)]$$
$$\frac{\partial n(x)}{\partial t} = D\Delta n(x)$$

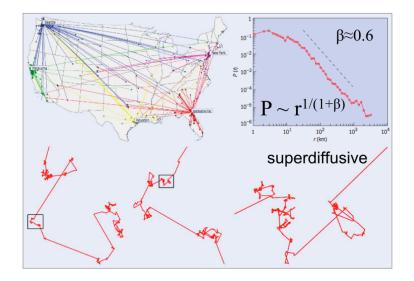
Dicrete:

$$\frac{\partial n_i}{\partial t} = \sum_i D_{ij} n_j$$

 \blacktriangleright What is D_{ij} ?

ightharpoonup Discrete Laplace operator D_{ij}

lacktriangle General: adjacency matrix: $D_{ij}=A_{ij}-k_j\delta_{ij}$



Rate equation n_k probability of finding the walker an a site with k edges:

$$\frac{\partial n_k}{\partial t} = -rn_k + k \sum_{k'} P(k'|k) \frac{r}{k'} n_{k'}$$

Uncorrelated random network:

$$P(k'|k) = \frac{k'}{\langle k \rangle} P_{k'}$$

New equation:

$$\frac{\partial n_k}{\partial t} = -rn_k + r \frac{k}{\langle k \rangle} \sum_{k'} P(k') n_{k'}$$

► Solution:

$$n_k = \frac{k}{\langle k \rangle N}$$



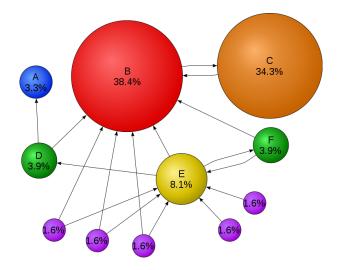
Page rank

- Do what surfers do
- ▶ Random walk on pages, but sometimes (probability q) a new (random) restart
- Self-consistent, equation:

$$P_R(i) = \frac{q}{N} - (1 - q) \sum_j A_{ij} \frac{P_R(j)}{k_{\text{out } j}}$$

Solution: iteration

Page rank example

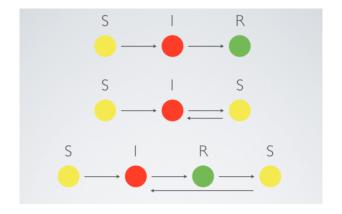


Disease spreding, SIR model

► S: susceptible

► I: Infected

R: Recovered



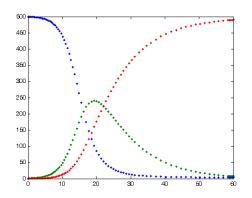
SIR model, connected graph

Governing equations:

$$\dot{S} = -\beta IS$$

$$\dot{I} = \beta IS - \nu I$$

$$\dot{R} = \nu I$$



Algorithm for the SIR model

- 1. List of initially infected nodes is I
- 2. Get a random (infected) node u from the list I
- 3. For all neighbors w of u do 4.
- 4. If w is susceptible change it to infected with probability β , and enqueue it into list I
- 5. With probability ν change state of u to recovered otherwise put it back to I
- 6. If I is not empty go back to 2.

Bit coding algorithm for the SIR model

- Ensemble average: each bit is a different instance
- ▶ Choose a link l which is between nodes n_i and n_j
- r is a random number with bits 1 of probability β (choose $\beta = 2^{-n}$ or similar)
- ▶ Passing disease: $p = [s(n_i)|s(n_j)]&r$
- ▶ Change states: $s(n_i)| = p$ and $s(n_j)| = p$
- A slightly different implementation than previous

Other agent based models

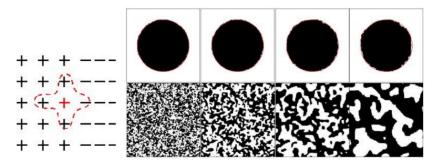
- Agents are nodes
- Interactions through links
- Any network:
 - Lattices
 - Random networkss
 - Scale-free
 - Fully connected graphs
- Examples:
 - Opinion models
 - ► Game models

Opinion models

- Agents have opinion x_i
 - ▶ binary ± 1 (yes/no)
 - discrete (parties)
 - continuous (views)
 - vector (different aspects)
- Interaction with other agents
 - pairwise
 - global (with mean)

Ising-model at T=0

- Result depends on the lattice type (surface tension)
- Phase transition
- For larger systems probability to reach order goes to zero in d > 2 (surface gets more important)
- Fully connected goes to order (no surface)

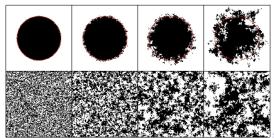


Voter model

Agents take opinion of random neighbor



- ightharpoonup d = 1,2 final state is consensus
- ▶ d>2 final state is not consensus, but a finite system reaches consensus after a time $\tau(N)\sim N$



Variants

- ► Majority rule (with two neighbors (3 nodes) towards majority)
- Presence of zealots, i. e. agents that do not change their opinion
- Presence of contrarians
- ► Three opinion states with interactions only between neighboring states
- Noise (with some probability p agents change their state)
- ▶ Biased opinion in case of a tie

Bounded confidence model: Deffuant model

- Agents have opinion x_i
- if $|x_i(t) x_i(t)| < \varepsilon$ then

$$x_i(t+1) = x_i(t) - \mu[x_i(t) - x_i(t)]$$

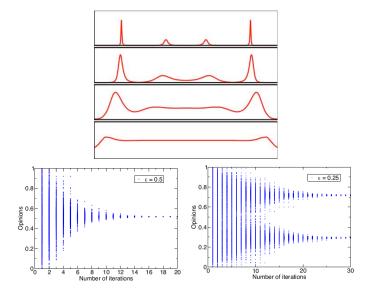
$$x_i(t+1) = x_i(t) + \mu[x_i(t) - x_i(t)]$$

- $lacktriangleq \mu$ compromise parameter $\mu=1/2$ complete compromise
- $\triangleright \varepsilon$ tolerance parameter
- ► Methods:
 - Monte-Carlo simulation
 - Master equation:

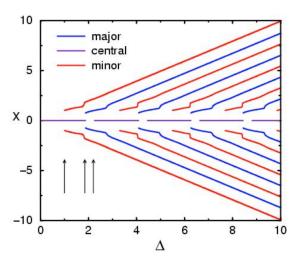
$$\frac{\partial P(x,t)}{\partial t} = \int_{|x_1 - x_2| < \varepsilon} dx_1 dx_2 P(x_1,t) P(x_2,t) \times \left[\delta \left(x - \frac{x_1 + x_2}{2} \right) - \delta(x - x_1) \right]$$



Deffuant model: Opinion groups (fully connected graph)



Deffuant model: Bifurcation diagram



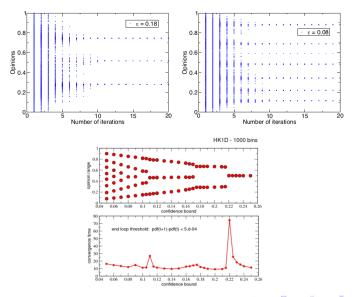
$$\Delta = 2/\varepsilon$$
, $\mu = 1/2$



Global: Hegselmann-Krause model

- Choose node i
- ► Test for all neighbors, which have opinion within the tolerance level
- Average their opinion
- ► Adapt to it
- Similar behavior

Hegselmann-Krause model



Game models:

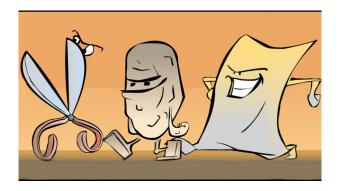
- ► Rock-paper-scissors
- Prisoner's dilemma
- ► Chicken, hawk-dove game

Game models:

- ► Rock-paper-scissors
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- ► Chicken, hawk-dove game

Rock-paper-scissors

- No winning strategy on (truly) random opponent
- ► E.g bacterian and antibiotics in mice
- Grass-rabbit-fox
- Popular in games



Prisoner's Dilemma

- ► Each player with a preferred strategy that collectively results in an inferior outcome
- Dominating strategy regardless of the opponent's action
- Nash equilibrium, from which no individual player benefits from deviating

	Cooperate	Defect
Cooperate	4, 4	1, 5
Defect	5, 1	2, 2

Prisoner's Dilemma

- ightharpoonup One game ightarrow defect
- ► Fixed number of games → defect
- Large pool of players (movie):
 - If other codes are known, it can be derived
 - If pool is diverse the best strategy is tit for tat (start with cooperation)
 - In general:
 - Nice (do not defect before opponent does)
 - Retaliating (punish!)
 - Forgiving (Yes!)
 - Non-envious (do not want to gain more than your neighbor)

Chicken game, Hawk-Dove game



Chicken game, Hawk-Dove game

- No preferred strategy
- ▶ The best strategy is to anti-coordinate with your opponent

	Cooperate	Defect
Cooperate	0, 0	-1, 2
Defect	2, -1	-5 , -5

- Example: Cold war
- Solution: anti-correlated pure strategy
- ▶ Probabilistic (play Hawk with p')







Chicken game, Hawk-Dove game difference to Prisoner's dilemma

	Cooperate	Defect
Cooperate	Reward	S, T
Defect	T, S	Punish

- Prisoner's dilemma: Temptation(T)>Reward(R)>Punish(P)>Sucker(S)
- Chicken game: Temptation(T)>Reward(R)>Sucker(S)>Punish(P)